

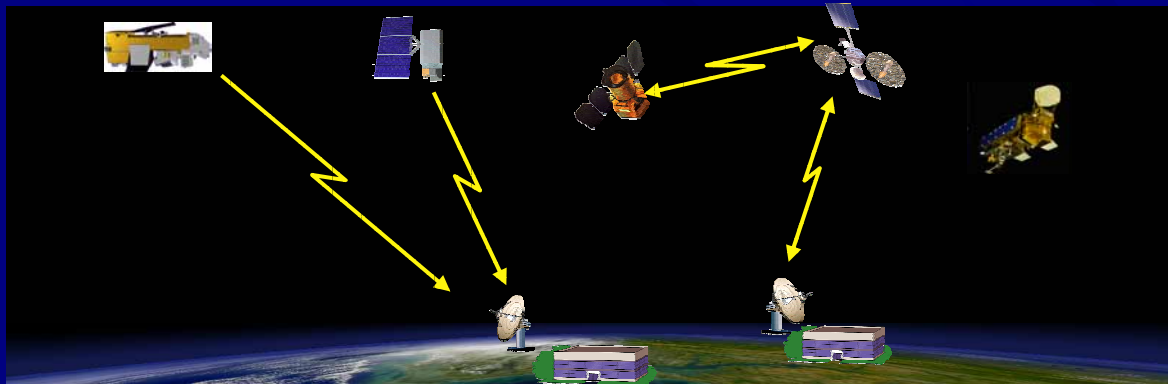


A Model-driven Sensor Web

586 / Stephen Talabac

Science Instruments & Missions - *Today*

- *“Stovepiped” measurements and mission ops concepts by single, independent science instruments and platforms*
- *No real time information sharing between instruments & platforms*
- *Interspacecraft communications - a “bent pipe” for command uplinks & science data downlinks*
- *With few exceptions, lacking in dynamic, reactive, and selectable, sensor measurement modes*
- *Lack of (near) real-time, interoperable planning & scheduling systems to facilitate opportunistic science and discovery*

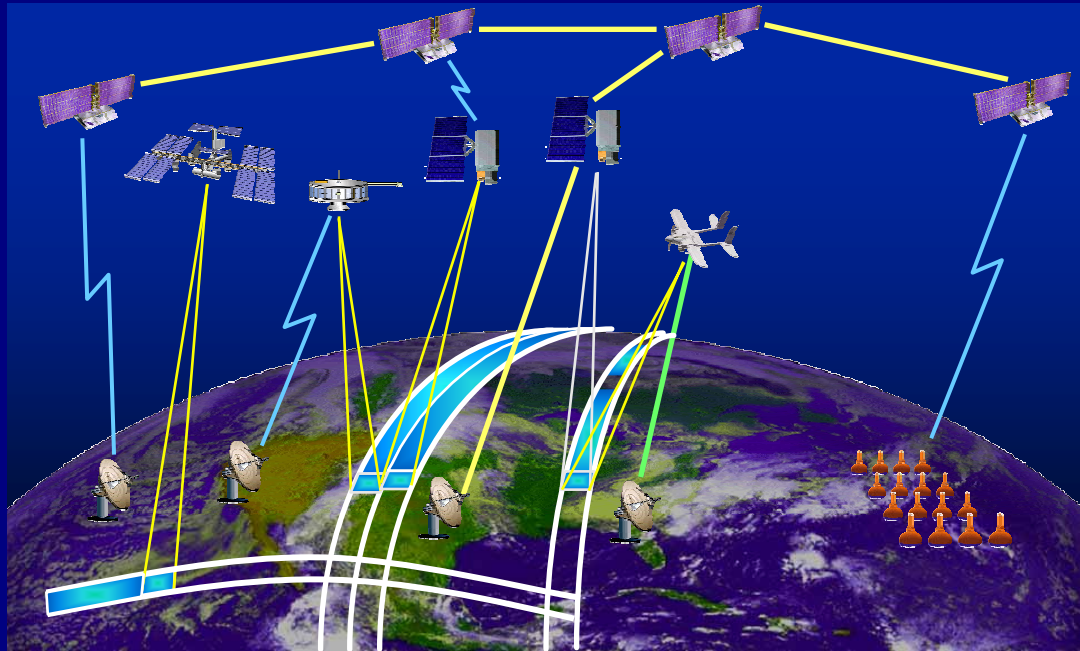


Sensor Webs - Tomorrow

"The best way to be ready for the future is to invent it."

John Sculley – CEO, Apple Computer

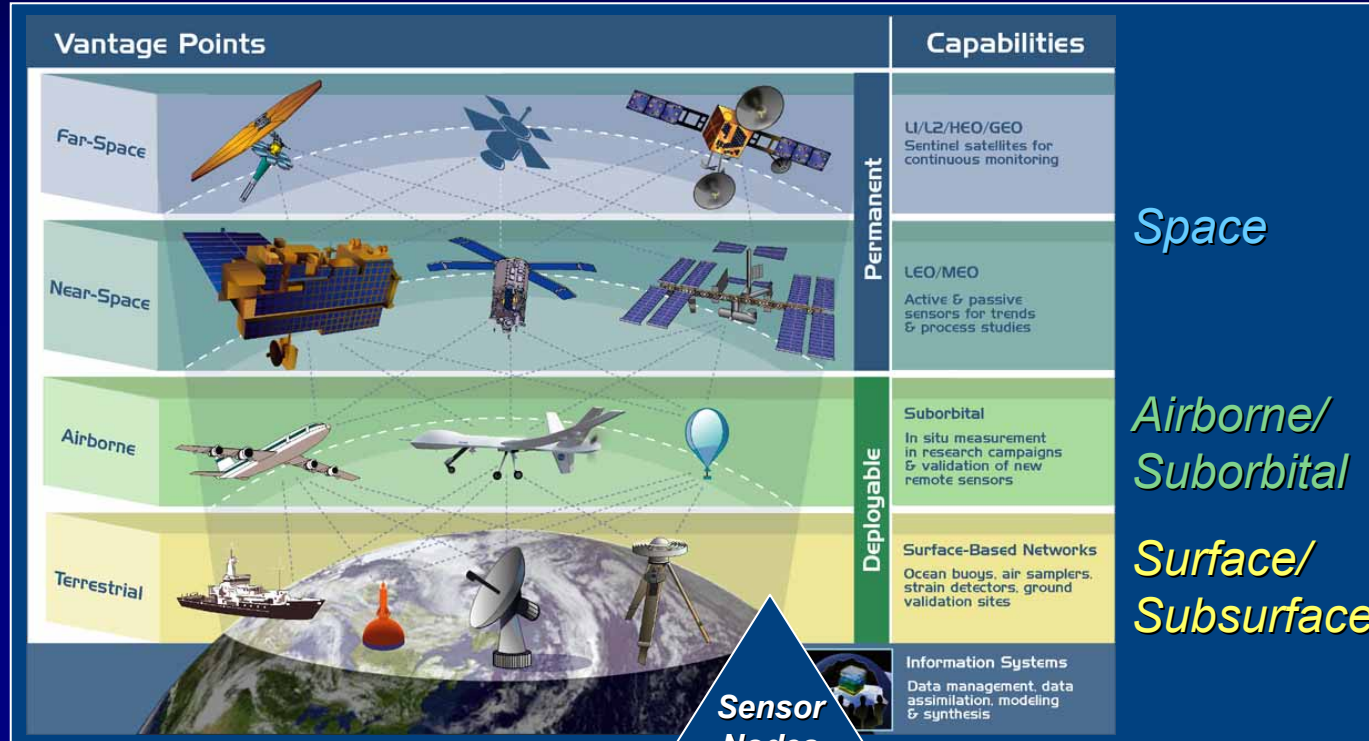
A sensor web is a coherent set of distributed “nodes”, interconnected by a communications fabric, that collectively behave as a single, dynamically adaptive, observing system.



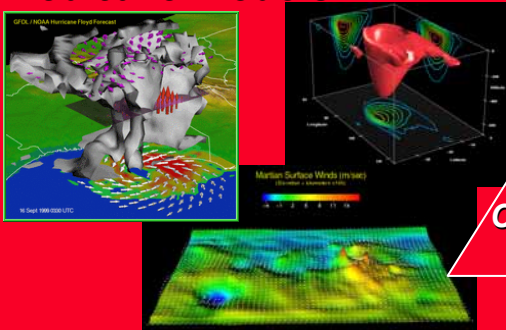
Sensor Webs: Adaptive Measurement Systems

"Life was simple before World War II. After that, we had systems."

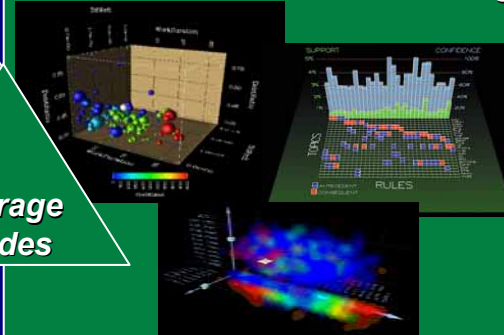
Rear Admiral Grace Murray Hopper



Predictive Models



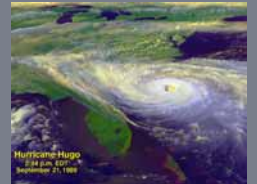
Data Fusion & Info Mining



Volcanic Ash Plume



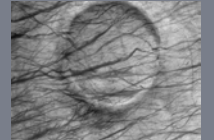
Hurricane



Io Lava flow



Mars Dust Devils



Gamma Ray Burst



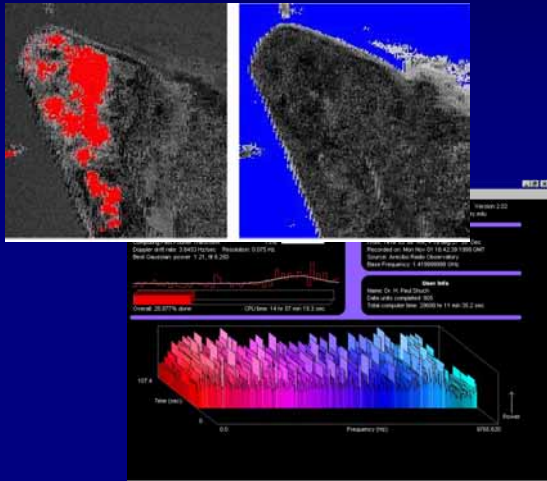
CME



Dynamic Space and Earth Science Events

Sensor Webs: Dynamic Node Interactions

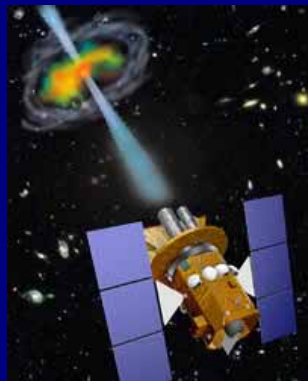
"Nothing endures but change. There is nothing permanent except change. All is flux, nothing stays still." Heraclitus



<i>Autonomous Node Interactions</i>	
Action	By...
<i>Perform multi-sensor data fusion</i>	<i>Synthesizing complementary sensor measurements</i>
<i>Identify signals and extract features, patterns, ...</i>	<i>Performing signal processing and signature detection, sensor correlation, image processing, ...</i>
<i>Modify science goals, re-plan observations, schedule new, targeted measurements</i>	<i>Establishing new goal priorities, exchanging sensor availability and operating state messages; identifying available sensor measurement services; ...</i>

then...

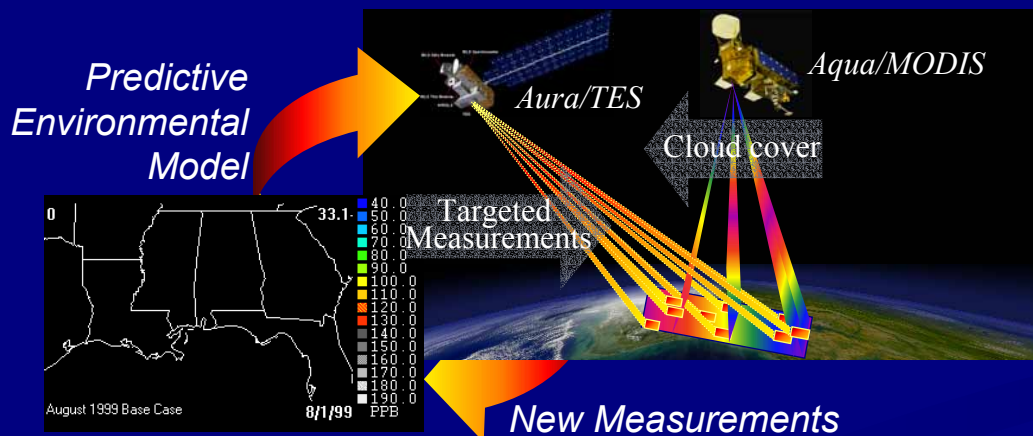
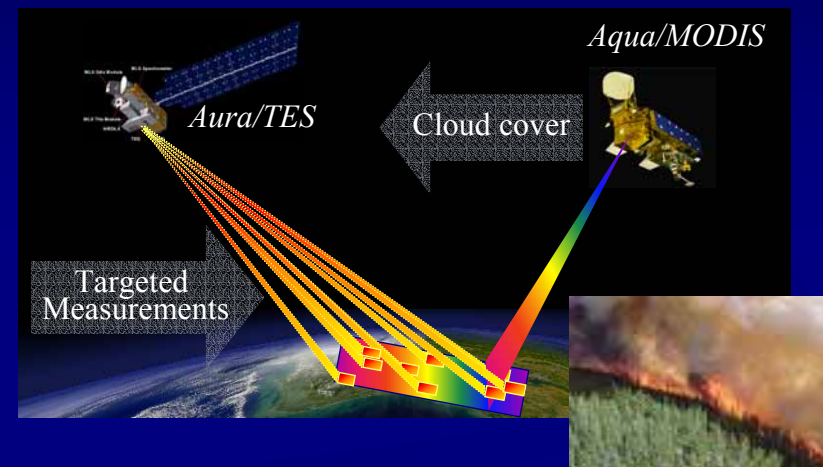
<i>Reconfigure Nodes & Perform New Measurements</i>	
Reconfiguration	Examples
<i>Temporal</i>	<i>Change sensor measurement frequency</i>
<i>Spatial</i>	<i>Deploy sensor to new location; change resolution, FOV, viewing geometry, ...</i>
<i>Spectral</i>	<i>Select only phenomenon-unique sensor bands</i>
<i>Assimilation & Models</i>	<i>Generate new initial conditions; invoke Mesoscale model; change model grid size, shape; ...</i>
<i>Organizational</i>	<i>Reform sensor clusters; form new node relationships, modify command and control hierarchy, ...</i>
<i>Hardware & software</i>	<i>Reconfigure programmable electronics; load and execute event specific algorithms, ...</i>



Sensor Web Observing Systems

Representative *Science and Applications Benefits*

- *Intelligent data collection*
...maximize useful science return by improved utilization of instruments and platforms
- *Event-driven observations*
...improve reaction time to observe rapidly evolving, transient, or variable events and phenomena



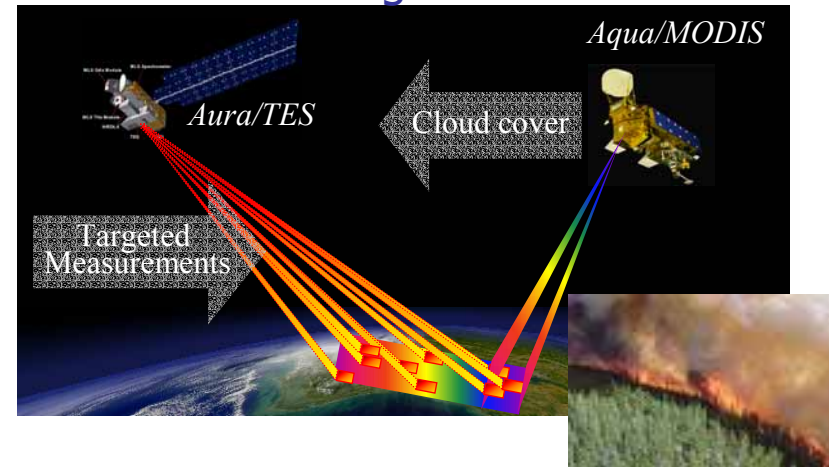
- *Model-driven observations*
... improve predictive skill and reduce forecast model error growth by using model outputs to initiate new, *targeted* sensor measurements

Background

FY04 Sensor Web IRAD

- Problem: (April 2003; Sensor Web Microworkshop, Mark Schoeberl)
 - It is undesirable for Aura's TES instrument, a pointable IR interferometer, to make measurements in cloud contaminated fields of view.
- Solution:
 - Use Aqua/MODIS data to generate cloud mask and identify cloud-free targets within TES FOV *in real time*.
 - Prototype system to demonstrate how dynamic measurement techniques can maximize useful science return.

Event-driven targeted observations



- Benefit:
 - Improved utilization of sensors, science instruments and platforms for real-time targeting applications.

Problem, Solution, Benefit

FY05 Sensor Web IRAD

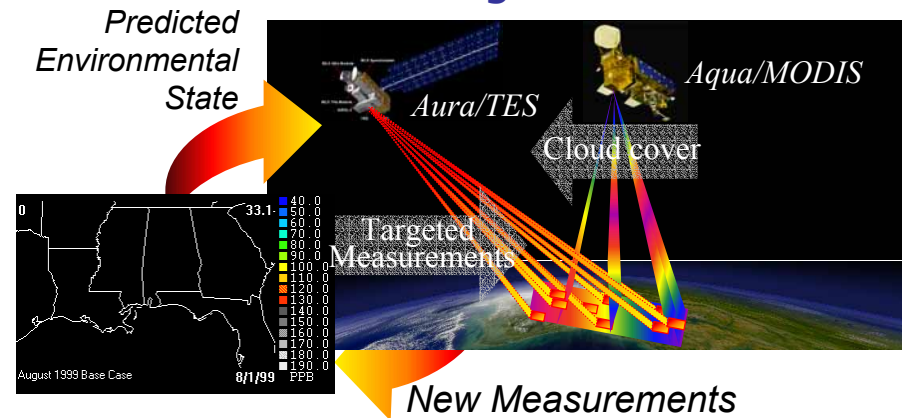
- Problem:

- It is desirable for Aura's TES to make targeted measurements where Tropospheric O₃ or other pollutants & precursors or are predicted to be significant.

- Solution:

- Implement atmospheric chemistry model to predict occurrence of O₃ or other pollutants and demonstrate model-driven targeting.

Model-driven targeted observations



- Benefit:

- Closed-loop feedback of new measurements into model can reduce forecast error growth and improve model predictive skill.



Approach

- Two principal objectives
 - Use atmospheric chemistry model output to drive targeted TES measurements
 - Identify and understand current Aura/TES operations; identify changes to accommodate Sensor Web ops concepts for future similar missions
- Characterize
 - Desired atmospheric chemistry model properties
 - TES measurement properties and mission observation modes



Approach - continued

- Identify available models for possible use and/or implementation
 - The Variable Grid Urban Airshed Model System (**UAM-V®**)
 - Models-3 Community Multiscale Air Quality (**CMAQ**) Modeling System (EPA, NOAA)
 - Global Ozone Chemistry Aerosol Radiation and Transport (**GOCART**) Model (Georgia Tech/Goddard)
 - Goddard Earth Observing System (GEOS) Chemistry Model (**GEOS-CHEM**)(Harvard University)



Approach - continued

- Characterize available models relative to:
 - Global vs. regional scale and available grid size(s)
 - Maturity and use by scientific community (NASA, NOAA, EPA, ...)
 - Run-time environment requirements & performance metrics
 - Initialization and external data inputs
 - Content & format of gridded output variables
 - Need for ancillary meteorological and/or emissions models
- Develop scenario and ops concept for using model output to drive dynamic, targeted TES measurements
 - TES *step-and-stare* vs. TES *transect* measurement modes
 - Where to make measurements within predicted regions of interest? (e.g., high O₃, CO, NOX concentrations)



Approach - continued

- Develop
 - System design (hardware, software)
 - Characterize interfaces to key external data sources and systems

- Develop I&T plan
 - Stand-alone model implementation and validation
 - Spiral system development, integration, and test



Approach - continued

- Determine current Aura/TES mission/instrument planning and scheduling, and commanding processes
- Formulate alternative architecture that incorporates event-driven and model-driven Sensor Web ops concepts into:
 - Future Aura/TES operations
 - Goddard mission & science instrument formulation processes
- Identify impact upon future ground-, space-, and communications segment infrastructure



Results, Status, Next Steps

- Status
 - Project kick-off Dec 7, 2004.
 - Characterizing candidate models and TES measurements

- Next steps
 - Select atmospheric chemistry model
 - Develop science scenario(s) for pollution “events”
 - Develop ops concept(s) for model-driven TES targeting
 - Mid-term review - Spring 2005

- Demonstrate/present findings - September 2005